Monte Carlo basics I

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UNIVERSIDAD DE GRANADA Milos Krstic presentation Online ELICSIR Summer School Radiation Effects in Electronic Devices, Circuits and Systems 26/07/2020

Multi-level SEE Modeling and Simulation





ABSTRACTION LEVELS



MOSFET used as dosimeters

MOSFET used as dosimeters



MOSFET used as dosimeters





-MOSFET response: energy deposited in the SiO2 die

MOSFET used as dosimeters





-MOSFET response: energy deposited in the SiO2 die

-very low statistics: 30 days for an uncertainty of 10% (k=3) [Intel Hapertown E5405 2.0 GHz]

Outline

- •Monte Carlo simulation of radiation-matter interaction
- •Sampling distributions
- •Some simple exercises





Monte Carlo techniques: procedures using random numbers to solve problems



<u>Monte Carlo techniques:</u>
 procedures using random numbers
 to solve problems



von Neumann y Ulam at Los Álamos (password)
 but: Comte de Buffon (18th. century)

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problems in which chance is essential:
 <u>simulation</u> of stochastic systems

 Monte Carlo techniques: procedures using random numbers to solve problems



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problems in which chance is essential:
 <u>simulation</u> of stochastic systems

 deterministic calculations reformulated in terms of probability distributions: calculation of integrals









electron/positron surface spectroscopy
electron microscopy
microanalysis with electron probe
design and use of radiation detectors
dosimetry
radiotherapy

⇒etc.



what are we trying to simulate?

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which material media are we interested in?

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homogeneous materials with uniform density

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- homogeneous materials with uniform density
 - -gases, liquids or amorphous solids
 - -particles are scattered randomly
 - -molecular weight: $A_{\rm M} = \sum n_i A_i$
 - -number of molecules per unit volume in the material: $\mathcal{N} = N_{\rm A} \frac{\rho}{A_{\rm M}}$

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let us assume that the particle interacts with the medium molecules via two mechanisms:
A and B

no secondary particle production



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 A and B
 - no secondary particle production
- -scattering model: $\frac{\mathrm{d}^2 \sigma_{\alpha}}{\mathrm{d}W \mathrm{d}\Omega}(E; W, \theta) \qquad \alpha = A, B$



 $W \equiv$ energy loss after the interaction $\Omega \equiv$ solid angle in the new direction

-scattering model: $\left| \frac{\mathrm{d}^2 \sigma_{\alpha}}{\mathrm{d}W \mathrm{d}\Omega} (E; W, \theta) \right| \alpha = \mathbf{A}, \mathbf{B}$



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$$\frac{\mathrm{d}^2 \sigma_{\alpha}}{\mathrm{d}W \mathrm{d}\Omega}(E; W, \theta) \quad \alpha = \mathbf{A}, \mathbf{B}$$

-partial cross sections:

 $\left| \sigma_{\alpha}(E) = 2\pi \int_{0}^{E} dW \int_{0}^{\pi} d\theta \sin \theta \frac{d^{2}\sigma_{\alpha}}{dWd\Omega}(E; W, \theta) \right|$



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-total scattering cross section:

$$\sigma_{\rm T}(E) = \sum_{\alpha \equiv \mathbf{A}, \mathbf{B}} \sigma_{\alpha}(E)$$





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 particle out of the material medium

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-charged particles, other energies, etc.

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-how to sample probability distributions?

<u>Random number generation</u> Uniform distibution U(0,1)

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Random number generation_ Uniform distibution U(0,1)- random numbers can be obtained in: physical processes of random character (radioactive processes, electric noise, etc.) $n_i \equiv$ number of disintegrations in Δt $d_i \equiv 0$ or 1 according n_i being even or odd 2 2 1 3 m n_i n_1 n_2 n_3 n_m . . . d_i

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- tables

(p.ej.: Abramowitz and Stegun)

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same results are obtained than using pseudo-ramdom numbers Random number generation_ Uniform distibution U(0,1) - pseudo-random numbers: Random number generation Uniform distibution U(0,1)

pseudo-random numbers:
obtained with the computer (!!!) Random number generation Uniform distibution U(0,1) - pseudo-random numbers: obtained with the computer (!!!)

- algorithms based on congruence relations

 $I_k = a I_{k-1} + c \pmod{M}$

Random number generation Uniform distibution U(0,1) - pseudo-random numbers: obtained with the computer (!!!)

- algorithms based on congruence relations

$$I_k = a I_{k-1} + c \pmod{M}$$

basic rules:
 generated numbers: uncorrelated
 sequence: as long as possible
 generating algorithm: as quick as possible

Carlsson algorithm



Press W H, Teukolsky S A, Vetterling W T and Flannery B P Numerical Recipes in Fortran 2nd ed. New York: Cambridge University Press, 1992

> FUNCTION RAN1(IDUM) INTEGER IDUM, IA, IM, IQ, IR, NTAB, NDIV REAL RAN1, AM, EPS, RNMX PARAMETER (IA=16807, IM=2147483647, AM=1./IM, IQ=127773, IR=2836, NTAB=32,NDIV=1+(IM-1)/NTAB,EPS=1.2E-7,RNMX=1.-EPS) > INTEGER J,K,IV(NTAB),IY SAVE IV, IY DATA IV /NTAB*0/, IY /0/ IF (IDUM.LE.0.OR.IY.EQ.0) THEN IDUM=MAX(-IDUM,1) DO J=NTAB+8,1,-1 K=IDUM/IO IDUM=IA*(IDUM-K*IQ)-IR*K IF (IDUM.LT.0) IDUM=IDUM+IM IF (J.LE.NTAB) IV(J)=IDUM CONTINUE IY=IV(1)ENDIF K=IDUM/IQ IDUM=IA*(IDUM-K*IQ)-IR*K IF (IDUM.LT.0) IDUM=IDUM+IM J=1+IY/NDIV IY=IV(J) IV(J)=IDUM RAN1=MIN(AM*IY, RNMX) RETURN END

Random number generation____ Other distributions

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inverse transform method
 (or variable change method)

- acceptance/rejection method

Metropolis method
 (or random walk method)

Random number generation____

Other distributions: inverse transform method
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Other distributions: inverse transform method

- to sample: uniform PDF



 $p(x) \equiv U(a,b) = \frac{1}{b-a}, \quad \forall x \in (a,b)$

Other distributions: inverse transform method

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$$p(x) \equiv U(a,b) = \frac{1}{b-a}, \quad \forall x \in (a,b)$$

$$\frac{\text{sampling equation}}{\xi = \int_{x_{\min}}^{x} \mathrm{d}y \, p(y)}$$

$$\xi = \int_{a}^{x} \mathrm{d}y \, \frac{1}{b-a} = \frac{x-a}{b-a}$$

Other distributions: inverse transform method

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$$x = a + (b - a)\xi, \ \xi \in U(0, 1)$$

Other distributions: inverse transform method



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$$p(x) = \frac{1}{\lambda} \exp\left(-\frac{x}{\lambda}\right), \quad x > 0$$

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Other distributions: inverse transform method

- to sample: Gaussian PDF

$$p_{\rm G}(x) = N(0,1) = \frac{1}{\sqrt{2\pi}} \exp\left(-\frac{x^2}{2}\right)$$

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Other distributions: inverse transform method

- to sample: Gaussian PDF

$$p_{\rm G}(x) = N(0,1) = \frac{1}{\sqrt{2\pi}} \exp\left(-\frac{x^2}{2}\right)$$

$$p(x_1, x_2) = p_G(x_1) p_G(x_2) = \frac{1}{2\pi} \exp\left(-\frac{x_1^2 + x_2^2}{2}\right)$$
$$p(x_1, x_2) dx_1 dx_2 = \left[r \exp\left(-\frac{r^2}{2}\right) dr\right] \left[\frac{1}{2\pi} d\phi\right]$$

$$\frac{\text{sampling equation}}{\xi = \int_{x_{\min}}^{x} \mathrm{d}y \, p(y)}$$

Other distributions: inverse transform method

- to sample: Gaussian PDF

p

p

$$p_{\rm G}(x) = N(0,1) = \frac{1}{\sqrt{2\pi}} \exp\left(-\frac{x^2}{2}\right)$$

$$(x_1, x_2) = p_{\rm G}(x_1) \, p_{\rm G}(x_2) = \frac{1}{2\pi} \, \exp\left(-\frac{x_1^2 + x_2^2}{2}\right)$$
$$(x_1, x_2) \, \mathrm{d}x_1 \, \mathrm{d}x_2 = \left[r \, \exp\left(-\frac{r^2}{2}\right) \, \mathrm{d}r\right] \left[\frac{1}{2\pi} \mathrm{d}\phi\right]$$

$$x_{1} = \sqrt{-2\ln\xi_{1}} \cos(2\pi\xi_{2}) , \quad \xi_{1}, \xi_{2} \in U(0, 1)$$
$$x_{2} = \sqrt{-2\ln\xi_{1}} \sin(2\pi\xi_{2})$$

Box-Müller method

sampling equation

 $\mathrm{d} y \, p(y)$

 $\xi =$

Other distributions: acceptance/rejection method



Random number generation Other distributions: acceptance/rejection method - to sample $p(E), E \in (0, E_{\max})$ -let us define $M \mid p(E) < M, \forall E \in [0, E_{\max}]$ M m_1 p(E) P_2 m_2 $E_{\rm max}$ E_2 E_1

E





Other distributions: Metropolis method

Other distributions: Metropolis method

- to sample any p(x)

 (x_0, D)

Other distributions: Metropolis method

$$(x_0, D) \longrightarrow \xi \in U(0, 1)$$

Other distributions: Metropolis method

$$(x_0, D) \longrightarrow \xi \in U(0, 1) \longrightarrow x_i = x_{i-1} + D(2\xi - 1)$$

Other distributions: Metropolis method

 $(x_0, D) \longrightarrow \left| \xi \in U(0, 1) \right| \longrightarrow \left| x_i = x_{i-1} + D(2\xi - 1) \right|$















Simple exercises

Sampling distributions

1. choose a probability distribution

Simple exercises

Sampling distributions

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2. sample the distribution using the algorithms just described
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- 3. build up the histogram corresponding to the numbers obtained in the sampling

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 4. compare distribution and histogram

- 1. choose a probability distribution
- 2. sample the distribution using the algorithms just described
- 3. build up the histogram corresponding to the numbers obtained in the sampling CHANGE BIN SIZE AND NUMBER!!!
 4. compare distribution and histogram NORMALIZATION!!!

Simple exercises Integral calculation

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 cE_{\max} I = $\mathrm{d}E\,p(E)$















N	N_{int}	π		
10	8	3.2±0.5		



N	$N_{ m int}$	π
10	8	3.2±0.5
100	78	3.12±0.17

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100	78	3.12 ± 0.17
1000	787	3.15±0.05

Simple exercises Integral calculation "crude" Monte Carlo method













Simple exercises Integral calculation: determination of π -we generate $p(x) = \sqrt{1 - x^2}$ $\{x_i \in U(0,1), i = 1, \dots, N\}$ $I = \frac{1}{N} \sum_{i=1}^{N} \sqrt{1 - x_i^2}$ i=1





Queue dynamics

-a simple problem: medical consultation

<u>Problem</u>: we want studying how the number of patients waiting in a medical consultation behaves and analyze possible strategies to proceed in the better (or not) way -determine the number of waiting patients in each moment -determine the waiting time of each of them

Ingredients:

- N_p patients appointed each t_{app} minutes
- $\boldsymbol{\cdot}$ consultation time: \boldsymbol{t}_c sample in a given PDF

$U(2 \min, 10 \min)$ N(5 min, 1 min)



$N(5 \min, 1 \min)$ $t_{app} + 1 \min * n$

 $t_{app} = 5 \min$

Waiting time for each patient (upper panels) and queue length as a function of time (lower panels) found for the uniform (left panels) and Gaussian (right panels) distributions.



Waiting time for each patient (left panel) and queue length as a function of time (right panel) obtained for the Gaussian distribution with the modified appointment schedule.



Thanks for the attention